# JUNGHYUN KIM

## INTERESTS

My research spans the domains of machine learning, natural language processing, computer vision, and robotics. I am dedicated to enabling intelligent agents to comprehend human language, with a focus on grounding of language to perception and action. My research objective is to empower agents to autonomously acquire an understanding of the real world with minimal human supervision.

## EDUCATION

Seoul National University Integrated Ph.D. in Artificial Intelligence, Advised by B.T.Zhang, Biointelligence Lab. – GPA: 4.27/4.3	Seoul, Korea 2021–Current
– Main Courses: DL, ML, AI, Pattern Recognition, RL, LLM, Cognitive Science, Neuroscie	ence, Data Science
Yonsei University B.S. in Electrical and Electronic Engineering	Seoul, Korea 2016–2021
<ul> <li>GFA: 4.15/4.5</li> <li>Main Courses: AI, Programming (C, Python, Matlab), Control Engineering, Mathematic Structure and Algorithms, Signals, Circuits, OS, Communication Theory, Wireless and M</li> <li>Yonsei Evison Award (2016), 1 highest honor(2020), 1 high honor(2020), 4 honors(2016, 2016)</li> </ul>	es, Probability, Data Iobile Networks 2017, 2019)
Experience	
Samsung AI EXPERT Program AI Teaching Assistant – Teaching Overall ML and Programming	Jun 2023
SurroMind Company Project — Large-scale Visual Reasoning Project (Develop a Baseline Visual Reasoning Model)	Aug-Dec 2022
POSCO DX AI Youth Challenge AI Mentor — Mentoring AI Projects for the Challenge	2022 - Current
Samsung AI Research Center, Samsung Adcanced Institute of Technology Course Project - SEM Depth Prediction via Auto Encoder	(SAIT) Jun 2022
CS, Seoul National University Teaching Assistant – Course: Artificial Intelligence	Mar-Aug 2022
Robotics and Mobile Networks Lab, EEE, Yonsei University Laboratory Internship	Summer 2019
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- Solving convex optimization problem using neural networks

#### **QUEBON AI Mathematics**

Company Internship

## PUBLICATIONS

INTERNATIONAL CONFERENCE

- [4] Socratic Planner: Inquiry-Based Zero-Shot Planning for Embodied Instruction Following S. Shin, S. Jeon, G. C. Kang, J. Kim, B. T. Zhang. arXiv preprint, 2024
- [3] PGA: Personalizing Grasping Agents with Single Human-Robot Interaction J. Kim, G. C. Kang\*, J. Kim\*, S. Yang, M. Jung, B. T. Zhang. arXiv preprint, 2024
- [2] PROGrasp: Pragmatic Human-Robot Communication for Object Grasping G. C. Kang, J. Kim, J. Kim, B. T. Zhang.
   *IEEE International Conference on Robotics and Automation* (ICRA 2024)
- [1] GVCCI: Lifelong Learning of Visual Grounding for Language-Guided Robotic Manipulation J. Kim, G. C. Kang\*, J. Kim\*, S. Shin, B. T. Zhang. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2023) Oral Presentation

DOMESTIC JOURNAL

 Tackling Entity Size-Based Bias in Visual Grounding J. Kim, G. C. Kang, H. Sul, B. T. Zhang. *KIISE Transactions on Computing Practices* (KTCP 2023)

Domestic Conference

- [6] Personalizing Large Language Models via Interest Trait Summarization J. Kim, B. T. Zhang. Korean Institute of Information Scientists and Engineers (KSC 2023)
- [5] Unsupervised Adaptation for Zero-shot Visual Grounding via Pseudo Query Generation J. Kim, B. T. Zhang. Korean Institute of Information Scientists and Engineers (KCC 2023)
- [4] Referring Expression Segmentation on Small Objects J. Kim, G. C. Kang, H. Sul, B. T. Zhang. *Korean Institute of Information Scientists and Engineers* (KSC 2022) Best Paper Presentation Award
- [3] Attention-based Text Augmentation Method for Referring Expression Segmentation J. Kim, G. C. Kang, H. Sul, B. T. Zhang. *Korean Institute of Information Scientists and Engineers* (KCC 2022)
- [2] Adaptive Spatial Comprehension via Object Relationship Learning with Home Robot

**J. Kim**, S. Lee, Y. Yoo, B. T. Zhang Korean Institute of Information Scientists and Engineers (KSC 2021)

[1] Prediction of Professional Golfer's Score by using Data Mining J. Kim

Korean Institute of Information Scientists and Engineers (KCC 2015)

#### THESIS

[1] Large-Scale Tiny Face Detection using MTCNN Bachelor's Thesis, Yonsei University, 2020

# PATENTS

- Method for Generating Artificial Intelligence Model Using Natural Language Instruction, Method and Apparatus for Driving Robot Using Said Artificial Intelligence Model
- Method and Apparatus for Generating Natural Language Instruction Based on Visual Recognition

# PROFESSIONAL ACTIVITIES

•	(Reviewing) IEEE Robotics and Automation Letters (RA-L)	2024
•	(Reviewing) IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)	2024

# INVITED TALKS

• A	AI SEOUL 2024, Seoul, Korea	Feb 2024
• A	AI Retreat, IPAI, SNU	Nov 2023
• ŀ	KOREA AI SUMMIT (spotlight session)	Nov 2023
• I	IEEE RO-MAN Workshop on Learning by Asking for Intelligent Robots and Agents	Aug 2023
• A	AI Symposium, AIGS, Korea	Aug 2023

#### SKILLS

- **Programming:** Python, C, Matlab, Verilog
- Robots: Kinova Gen3, UR5, Pepper

#### LANGUAGES

- Korean (Native)
- English (New TEPS: 483)

## EXTRACURRICULAR ACTIVITIES

•	Professional Golf Caddie	2021-2022
	Professional Golf Tour in Asia & Korea Professional Golfers' Association (KPGA) Korean Golf Tour	
•	Seoul Junior Athletics Championships $2^{nd}$ place in Seoul, Korea	2014
•	Korea Junior Golf Association Junior Golfer	2011-2013